

Neuroendoscope Holder and Brain Retractor

Presented By:

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Neuroendoscopy

What is a Neuroendoscopy?

- **Neuroendoscopy** is a minimally-invasive surgical procedure in which the neurosurgeon removes the tumor through small holes in the skull or through the mouth or nose.

Neuroendoscopy enables neurosurgeons to:

- Access areas of the brain that cannot be reached with traditional surgery
- Remove the tumor without cutting or harming other parts of the skull

Neuroendoscopy results in:

- Less pain than traditional surgery
- Faster recovery than traditional surgery
- Minimal scarring

Advantages of Neuroendoscopy

The neurosurgeon can see into the brain to an extent that was not previously possible with a microscope and can carry out more extensive surgery. Neuroendoscopy provides:

- Panoramic views
- Better observation
- Additional illumination
- Increased overview
- Higher magnification
- Can 'look around corners'
- Extended viewing angles
- Provides a 'second perspective'
- Excellent visual quality in deep narrow fields

Concerns while using Neuroendoscope

- Endoscopic surgery requires special training and experience.
- Bloody operative field (needs constant cleaning of lens).
- Fogging is also a problem and needs endoscope to be removed and cleaned when it occurs.
- There is risk of local injury to the surrounding structures.
- Movements of instruments are restricted due to the small diameter of the working channel.
- Limited working channels due to small diameter of the operating sheath.

What is a Endoscope holder?

- An endoscope holder is a device used to mount and fix the endoscope in a particular position.
- It acts as a third arm of the surgeon.
- Articulated arm allows movements in different directions.
- Provides some degree of freedom even if the frame is fixed.

Free hand vs. Endoscope holder

Neuroendoscopy can be done either free hand or using a rigid holder. The table lists advantages and disadvantages of both:

	Free Hand	Using Holder
Advantages	<ol style="list-style-type: none">1. More freedom of movement particularly when configuration needs to be frequently changed, e.g. tumor removal	<ol style="list-style-type: none">1. Surgeon can use both hands2. Minimizes accidental movements and tremor
Disadvantages	<ol style="list-style-type: none">1. More fatigue for surgeon2. Risk of accidental movements	<ol style="list-style-type: none">1. More static2. Inconvenient when frequent repositioning is needed

Available Technologies

Mechanical Holding Arm



Features:

- Rotation socket to clamp to operating table
- Articulated Stand for all five joint functions
- Clamping Jaw for use with the instrument (range 4.8 to 12.5mm)

Pneumatic Holding Arm



Features:

- Direct connection to OR compressed air supply
- Integrated safety system prevent collapsing of holding arm
- Single handed use
- Precise and fine steering

Motorized Holding Arm

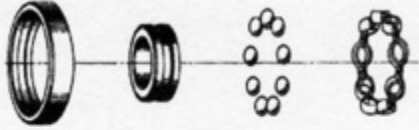


Features:

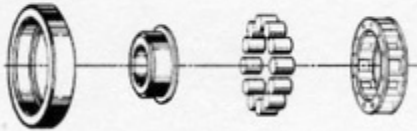
- Electronically Powered
- Powerful
- Increased precision
- Direct control through foot switch
- Used in laparoscopic and thoracoscopic surgeries

Mechanical

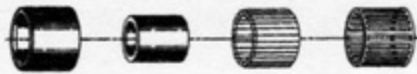
BALL BEARINGS



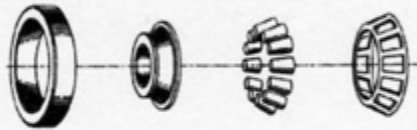
CYLINDRICAL ROLLER BEARINGS



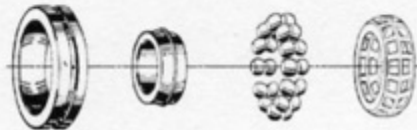
NEEDLE ROLLER BEARINGS



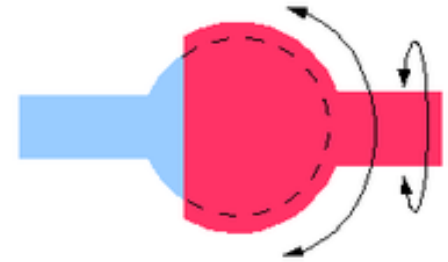
TAPERED ROLLER BEARINGS



SPHERICAL ROLLER BEARINGS



A typical ball joint with cutaway view

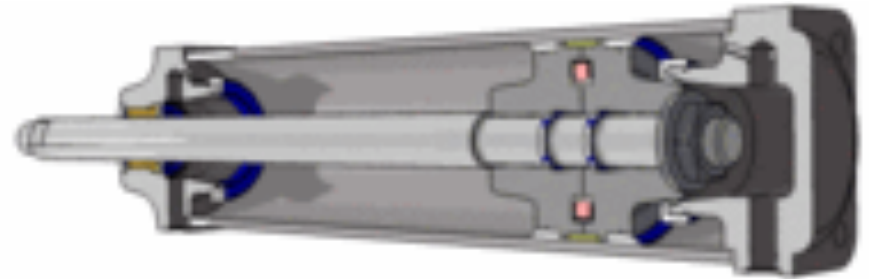


- A ball joint is used for allowing free movement in two planes at the same time, including rotating in those planes.
- Combining two such joints with control arms enables motion in all three planes.
- Ball joints allow a limited range of smooth movement in all directions

Pneumatic

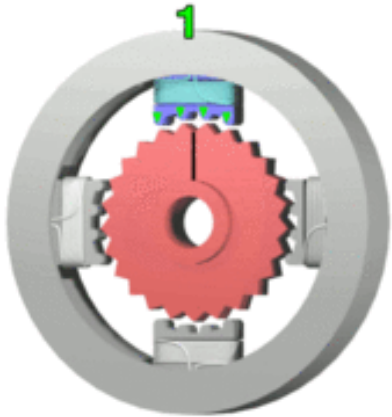


- The word "pneumatic" comes from the Greek and refers to air.
- The pneumatic retraction and holding system for open as well as for minimally-invasive surgery, neurosurgery, orthopaedics and traumatology.

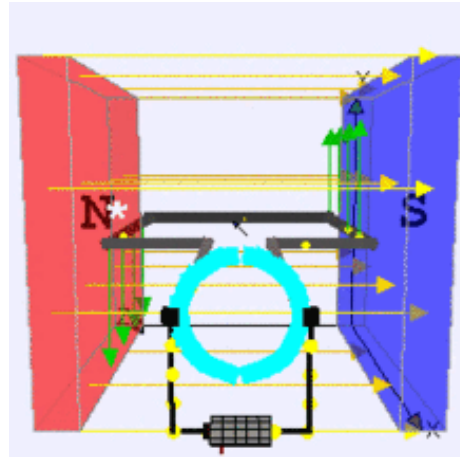


- A pneumatic cylinder uses the pressure of a gas to perform work.
- It is less expensive and normal air is the most common type of gas used in pneumatic cylinders.
- Air can be easily taken in and compressed to refill pneumatic systems.

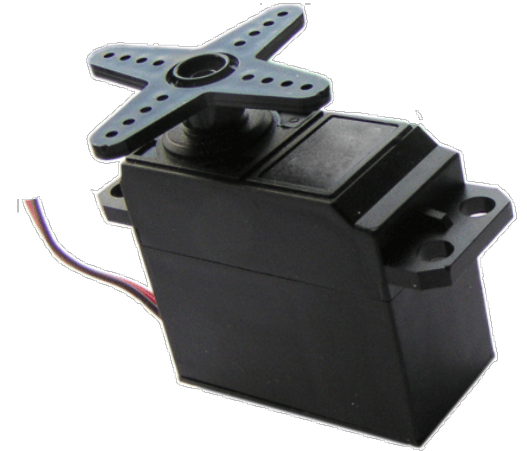
Motorized



- A **stepper motor** (or **step motor**) is a electric motor that divides a full rotation into a number of equal steps.
- Available in different step angles ranging



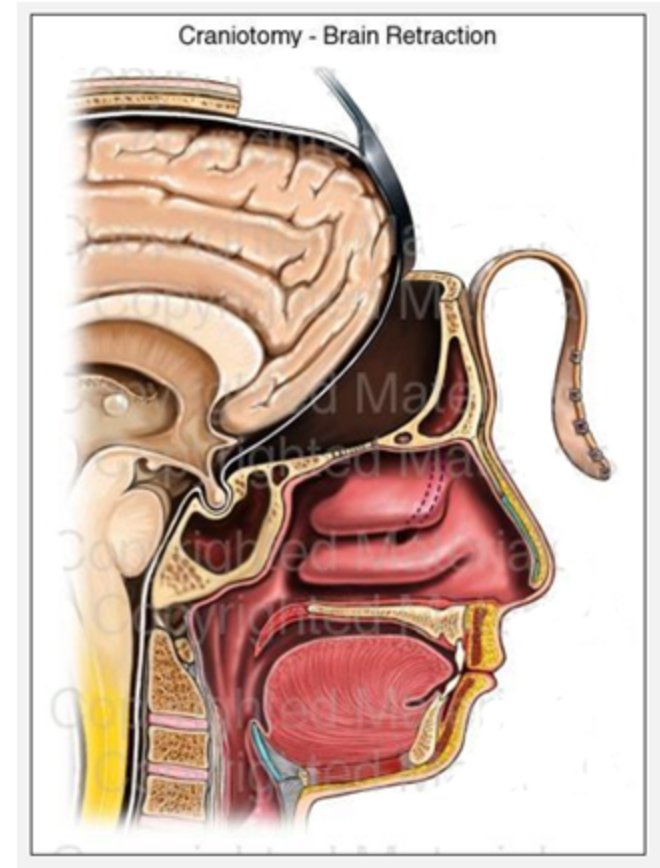
- The **DC motor** generates torque directly from DC power supplied to the motor by using internal commutation, stationary permanent magnets.
- The commutator consists of a split ring, so that the current reverses each half turn.



- A **servomotor** is a rotary actuator that allows for precise control of angular position.
- They consist of a motor coupled to a sensor for position feedback, through a reduction gearbox.

Brain Retraction

- Brain retraction is the method to hold brain tissues at a particular position for better exposure of the operative target or site.
- It is still one of the most important techniques to lessen brain damage.
- It can be achieved by handheld (by surgical assistant) or self retaining retractors.



Self retaining retractors

Self retaining retraction system consists of certain common features:

- The rod/post- It is attached to a rigid structure. It provides the stability and fix base to the retraction system.
- Flexible arms- These form the intermediate link between the retractor blade and the fixed rod/post. They consist of series of small metal pieces joined to each other by ball and socket joints.
- Brain Spatulas- These are flat, malleable blades of different shapes. The portion of the brain and amount of brain to be retracted would dictate the choice of a particular blade. Another characteristic of these blades is that they have non-reflective surface to minimize glare from reflective light used.



1. Brain spatula
2. Flexible arm
3. Rod/Post

Classification

The self retaining systems available can be broadly classified into four categories:

1. Skull mounted devices-

These were earlier retractor systems. These were rods mounted in a drill hole in the skull with attached retractor.

2. Soft tissue mounted devices –

These are secured by tension in the muscles and soft tissue but because of the relative mobility are inherently unstable.

3. Table mounted flexible arm systems –

They are basically modification of flexible arm system. This system consist of angulated rod, which is fixed to the operating table.

4. Head rest mounted systems –

in these systems, the base plate is attached to the skull clamp.

Thank You